

Tentative plan for the alternating reading groups

Data	Time	Speaker	Reading	Topic
20-Jan	15.00-16.00	Abdul	RP	Chapter 1: Introduction to RP, classical ODE with forcing, fail of continuity of solution map when forcing is less regular
27-Jan	13.00-14.00	Billy	SML	Section 1.1.1-1.2.2: Paths in Euclidean spaces, definition of signatures and examples
3-Feb	15.00-16.00	Enoch	RP	Section 2.1-3.1: Holder spaces, mostly definitions and basic properties and “Holder spaces” of 2-parameter functions, Space of Rough Paths, i.e. level-2 enhancement of Holder spaces
10-Feb	13.00-14.00	Tim	SML	Section 1.2.3-1.3.3: Motivation for signature (through Picard iteration), geometric intuition and invariance under time paramterisation
17-Feb	15.00-16.00	Jacob	RP	Section 3.1-4.3: Geometric Rough Paths and Brownian motion as a rough path through Kolmogorov continuity criterion
24-Feb				CANCELLED DUE TO PROBABILITY NORTH EAST MEETING
3-Mar	15.00-16.00	Miles	RP	Section 5.1-5.2: Sewing Lemma (the major tool in integration, shows existence of integral bases on local approximations) and Young integration
10-Mar	13.00-14.00	Abdul	SML	Section 1.3.2-2.1.2: Shuffle product, Chen’s identity, Time-reversal and log-signature; Paths from discrete data and the lead-lag transformation
17-Mar	15.00-16.00	Billy	RP	Section 5.3-5.4: Rough integration, existence of integral through Sewing Lemma (and continuity properties)
24-Mar	13.00-14.00	Miles	SML	Section 2.1.3-2.1.5: signatures of path, more elementary operations with signatures and computing statistical moments from signatures
31-Mar	15.00-16.00	Tim	RP	Chapter 6: Rough integrals, properties as associativity and Ito-formula
7-Apr	15.00-16.00	Jacob	SML	Section 2.2-2.4: The signature in machine learning and overview of recent progress of the signature method in machine learning
14-Apr	15.00-16.00	Jacob	RP	Chapter 7: Differential equations (Young and Rough DEs)
21-Apr	15.00-16.00		SML	More stuff if there is interest?
28-Apr	15.00-16.00	Deven	RP	Chapter 8: Consistency with Ito integration, i.e. showing that classical Ito calculus gives the same solutions to SDE as Rough DEs
5-May	15.00-16.00	Deven	RP	Chapter 10: Pathwise filtering and optimal control